

Symbolic-Numeric Factorization of Linear Differential Operators

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Factorization of differential operators

Object of study: linear differential operator

$$P = a_r \partial^r + a_{r-1} \partial^{r-1} + \cdots + a_1 \partial + a_0 \in \mathbb{K}(x) \langle \partial \rangle$$

for a number field $\mathbb{K} \subset \mathbb{C}$, $a_i \in \mathbb{K}(x)$, $a_r \neq 0$, and $\partial = d/dx$

Commutation rule: $\partial x = x \partial + 1$ Leibniz: $(xf)' = xf' + f$

Goal

Find $L, R \in \overline{\mathbb{K}}(x) \langle \partial \rangle$ of order > 0 such that $P = LR$

Example:

$$x\partial^2 + (-4x^3 + 5x)\partial + 4x^2 - 5 = (\partial - 4x^2 + 5)(x\partial - 1)$$

History: around factorization algorithms

1894 Beke

hyperexponential solutions
+ exterior power method

1996 Singer

eigenring method

1997 van Hoeij

local-to-global method
➤ Maple DEtools package

2004 Cluzeau, van Hoeij

modular approach

2007 van der Hoeven

symbolic-numeric approach
➤ SageMath package (new)

2013 Johansson, Kauers, Mezzarobba

hyperexponential solutions by symbolic-numeric approach

2014 Lorente

Liouvillian solutions by symbolic-numeric approach

Improvements of Beke's algorithm

1989 Schwarz

1990 Grigor'ev
(complexity analysis)

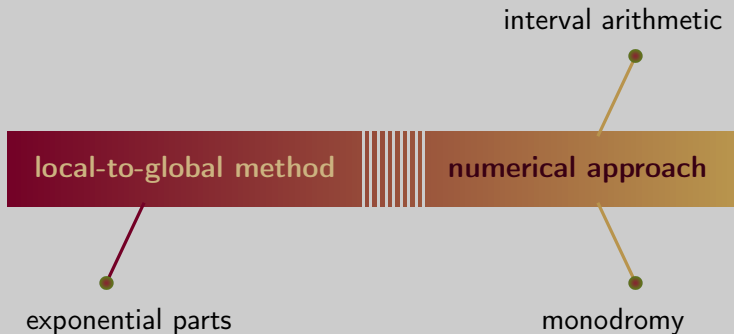
1994 Bronstein

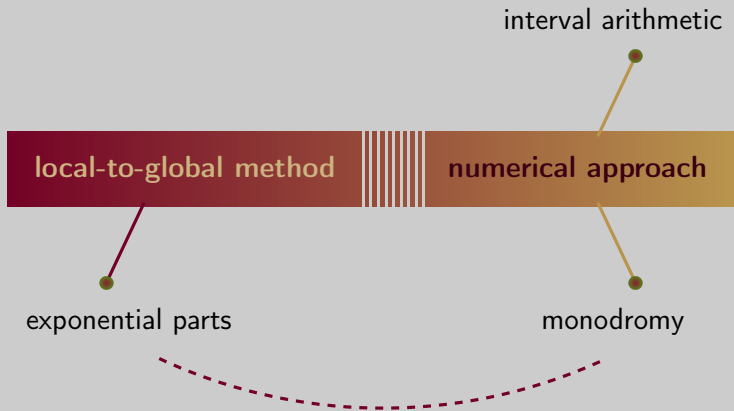
1996 Tsarev

local-to-global method



numerical approach





Local solutions at a nonsingular point

Definition: $\Sigma(P) := \bigcup_{i=0}^{r-1} \left\{ \text{poles of } \frac{a_i}{a_r} \right\} \subset \mathbb{P}^1(\mathbb{C})$ (singularities)

Cauchy-type theorem:

If $x_0 \in \mathbb{C} \setminus \Sigma(P)$ then there is a basis (f_0, \dots, f_{r-1}) of solutions such that:

$$\forall 0 \leq i, j < r, f_i \in \mathbb{K}[[x - x_0]] \quad \text{and} \quad f_i^{(j)}(x_0) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases} .$$

Throughout this talk

- $0 \notin \Sigma(P)$
- $\text{Sol}(P) := \text{Span}_{\mathbb{C}}(f_0, \dots, f_{r-1})$ space of local solutions at 0
- Identification: $\text{Sol}(P) \ni f \longleftrightarrow \text{coord}(f) \in \mathbb{C}^r$

Differential Galois group
and
monodromy

$$E := \mathbb{C}(x)(f_0, \dots, f_{r-1}, f'_0, \dots, f'_{r-1}, \dots, f_0^{(r-1)}, \dots, f_{r-1}^{(r-1)})$$

Picard-Vessiot extension

$$\text{Gal}_{\text{diff}}(P) := \{ \sigma \in \text{Aut}(E/\mathbb{C}(x)) \mid \forall f \in E, \sigma(f') = \sigma(f)'\}$$

► left action of $\text{Gal}_{\text{diff}}(P)$ on $\text{Sol}(P)$

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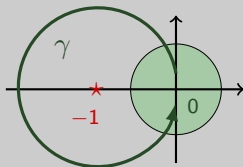
Theorem: $\text{Gal}_{\text{diff}}(P)$ is a linear algebraic group.

Faithful representation: $\psi : \sigma \mapsto M \in \mathbb{C}^{r \times r}$ such that

$$\forall f \in \text{Sol}(P), \text{coord}(\sigma(f)) = M \times \text{coord}(f)$$

► left action of $\mathcal{G} := \psi(\text{Gal}_{\text{diff}}(P))$ on \mathbb{C}^r

Example/Definition: $Q = (x + 1)\partial^2 + \partial$ admits $f_0 := 1$, $f_1 := \log(1 + x)$ as basis of solutions

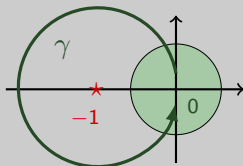


$$af_0 + bf_1 \xrightarrow{\text{analytic continuation along } \gamma} (a + 2i\pi b)f_0 + bf_1$$

$$\begin{pmatrix} a \\ b \end{pmatrix} \xrightarrow{\quad} \begin{pmatrix} a + 2i\pi b \\ b \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 2i\pi \\ 0 & 1 \end{pmatrix}}_{\text{local monodromy matrix around } -1} \begin{pmatrix} a \\ b \end{pmatrix}$$

local monodromy matrix around -1

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local monodromy matrix around -1

$\mathbb{C}^{r \times r} \supset \mathcal{M} :=$ group generated by all the local monodromy matrices of P

Remark: rigorous arbitrary-precision computation of monodromy matrices available in the SageMath package `ore_algebra` [Mezzarobba, 2016]

Theorem [Schlesinger, 1885]

If P is Fuchsian then $\mathcal{G} = \overline{\mathcal{M}}$ (for the Zariski topology).

Fuchs' criterion, 1866: The operator P is Fuchsian if and only if the fraction $\frac{a_i}{a_r}$ has no pole in $\mathbb{P}^1(\mathbb{C})$ of order $< i - r$, for each $0 \leq i < r$.

Theorem [Ramis, 1995] $\mathcal{G} = \overline{\mathcal{M} + \text{the exponential torus} + \text{the Stokes matrices}}$

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Remark: If P is Fuchsian then, for $\sigma \in \Sigma(P)$, there is a basis of solutions of the form

$$f(x) = (x - \sigma)^\alpha \sum_{j=0}^d s_j (x - \sigma) \log(x - \sigma)^j \quad \text{where} \quad \begin{cases} \alpha \in \overline{\mathbb{K}}, \\ d \in \mathbb{Z}_{\geq 0}, \\ s_0, \dots, s_d \in \overline{\mathbb{K}}[[x]]. \end{cases}$$

Moreover $(x - \sigma)^\alpha = e^{\alpha \log(x - \sigma)} \longrightarrow e^{2i\pi\alpha} (x - \sigma)^\alpha$ after \circlearrowleft .

Therefore: exponential parts \Leftrightarrow eigenvalues of the local monodromy matrix

$:= \alpha + \mathbb{Z}$, see [van Hoeij, 1996]

$$\mathcal{A} := \mathbb{C}[\mathcal{M}] \subset \mathbb{C}^{r \times r} \quad (\text{group algebra})$$

Proposition: There is a one-to-one correspondence:

$$\begin{array}{ccc} \text{right-hand factor } R \text{ of } P & \longleftrightarrow & \mathcal{A}\text{-submodule } V \text{ of } \mathbb{C}^r \\ & & V \simeq \text{Sol}(R) \end{array}$$

Strategy for finding a right-hand factor

[van der Hoeven, 2007]

1. Loop over precision until success:
2. Compute approximations of the local monodromy matrices
3. Search for an approximate nontrivial proper \mathcal{A} -submodule V
4. If no such V exists then
5. Exploit error bounds to ensure the irreducibility
6. Else guess a symbolic $R \in \overline{\mathbb{K}}(x)\langle\partial\rangle$ from V and check it

Norton's criterion

or: how to adapt the local-to-global method
to the module framework?

Finding a submodule

Assume that P admits a nontrivial factorization $P = LR$.

$\tilde{\mathcal{A}} := T^{-1}\mathcal{A}T$ where $T :=$ transition matrix from (f_0, \dots, f_{r-1}) to a basis adapted to a decomposition $\text{Sol}(P) = \text{Sol}(R) \oplus S$.

Remark: Any $M \in \tilde{\mathcal{A}}$ has a block-triangular form $\left(\begin{array}{c|c} M_R & * \\ \hline 0 & M_L \end{array} \right)$.

If there is $M \in \tilde{\mathcal{A}}$ with a simple eigenvalue λ ,
let $v \in \mathbb{C}^{r \times 1}$, $w \in \mathbb{C}^{1 \times r}$ be such that $Mv = \lambda v$, $wM = \lambda w$, then

either λ is an eigenvalue of $M_R \Rightarrow \tilde{\mathcal{A}}v \not\subseteq \mathbb{C}^{r \times 1}$,
or λ is an eigenvalue of $M_L \Rightarrow w\tilde{\mathcal{A}} \not\subseteq \mathbb{C}^{1 \times r}$.

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Remark: in the local-to-global method:

e is an exponential part of multiplicity 1 of $P \Rightarrow$ either e is an exponential part of R
or e is an exponential part of L

Theorem: Given $M \in \mathcal{A}$, a simple eigenvalue λ , and nonzero $v \in \mathbb{C}^{r \times 1}$, $w \in \mathbb{C}^{1 \times r}$ satisfying $Mv = \lambda v$, $wM = \lambda w$, the following statements are equivalent:

- (1) the left \mathcal{A} -module $\mathbb{C}^{r \times 1}$ is irreducible,
- (2) $\mathcal{A}v = \mathbb{C}^{r \times 1}$ and $w\mathcal{A} = \mathbb{C}^{1 \times r}$,
- (3) the right \mathcal{A} -module $\mathbb{C}^{1 \times r}$ is irreducible.

Note: right action of \mathcal{A} on $\mathbb{C}^{1 \times r} \longleftrightarrow$ monodromy action on $\text{Sol}(P^*)$
 $P^* :=$ image of P by the anti-endomorphism of $\mathbb{K}(x)\langle\partial\rangle$ mapping ∂ to $-\partial$
(so that $(LR)^* = R^*L^*$)

Interval arithmetic

or: how to certify independence?

Implementing basic operations $+$, $-$, \times , \div , $\sqrt{\cdot}$, \dots on intervals:

Motto

The interval contains the exact value.

Example: Let $\pi := [3.1415, 3.1416]$ be an interval representing π . We require that $\sqrt{\pi} \supset \{x \in \mathbb{R} \text{ such that } 3.1415 \leq x^2 \leq 3.1416\}$.

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Difficulties

- Overestimation
- Testing the nullity

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Extensions

- Complex numbers
- Vectors, matrices

$$\begin{pmatrix} [3.14, 3.15] & [3.33, 3.34] & [1.72, 1.73] \\ [2.41, 2.42] & [3.55, 3.56] & [2.14, 2.15] \\ [-0.7, -0.69] & [1.27, 1.28] & [5, 5.01] \end{pmatrix}$$

Operation: $r_1 \leftarrow r_1/c_{11}$

$$\begin{pmatrix} \mathbf{1} & [1.05, 1.07] & [0.54, 0.56] \\ [2.41, 2.42] & [3.55, 3.56] & [2.14, 2.15] \\ [-0.7, -0.69] & [1.27, 1.28] & [5, 5.01] \end{pmatrix}$$

Interval Gaussian elimination

Operations: $r_2 \leftarrow r_2 - c_{21}r_1$ and $r_3 \leftarrow r_3 - c_{31}r_1$

$$\begin{pmatrix} 1 & [1.05, 1.07] & [0.54, 0.56] \\ 0 & [0.96, 1.03] & [0.78, 0.85] \\ 0 & [1.99, 2.04] & [1.64, 1.68] \end{pmatrix}$$

Interval Gaussian elimination

Operations: $r_2 \leftrightarrow r_3$ then $r_2 \leftarrow r_2/c_{22}$ and $r_3 \leftarrow r_3 - c_{32}r_2$

$$\begin{pmatrix} 1 & [1.05, 1.07] & [0.54, 0.56] \\ 0 & 1 & [0.8, 0.85] \\ 0 & 0 & [-0.1, 0.09] \end{pmatrix}$$

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number of “interval pivots” \leq rank of the exact matrix

Correction of interval Gaussian elimination

Notation: $\mathbb{C}_\bullet := \{\mathcal{B}(c, \epsilon); c \in \mathbb{C}, \epsilon \in \mathbb{R}_{\geq 0}\}$ the set of balls

Proposition 1:

Given $\mathbf{v}_1, \dots, \mathbf{v}_p \in \mathbb{C}_\bullet^r$, we can compute $\mathbf{u}_1, \dots, \mathbf{u}_t \in \mathbb{C}_\bullet^r$ such that:
for all $v_1 \in \mathbf{v}_1, \dots, v_p \in \mathbf{v}_p$, there are $u_1 \in \mathbf{u}_1, \dots, u_t \in \mathbf{u}_t$ satisfying:

- (u_1, \dots, u_t) is linearly independent,
- $\text{Span}_{\mathbb{C}}(u_1, \dots, u_t) \subset \text{Span}_{\mathbb{C}}(v_1, \dots, v_p)$.

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Proposition 2: Let $v_1, \dots, v_p \in \mathbb{C}^r$ be fixed.

If $\mathbf{v}_1, \dots, \mathbf{v}_p \in \mathbb{C}_\bullet^r$ are such that $v_1 \in \mathbf{v}_1, \dots, v_p \in \mathbf{v}_p$ then:

“the \mathbf{v}_i are precise enough” \Rightarrow “the inclusion \subset is an equality”.

Correction of orbit computation

Corollary 1:

Given $\mathbf{M}_1, \dots, \mathbf{M}_k \in \mathbb{C}_{\bullet}^{r \times r}$, $\mathbf{v} \in \mathbb{C}_{\bullet}^r$, we can compute $\mathbf{w}_1, \dots, \mathbf{w}_d \in \mathbb{C}_{\bullet}^r$ such that:

for all $M_1 \in \mathbf{M}_1, \dots, M_k \in \mathbf{M}_k$, $v \in \mathbf{v}$, there are $w_1 \in \mathbf{w}_1, \dots, w_d \in \mathbf{w}_d$ satisfying:

- ▶ (w_1, \dots, w_d) is linearly independent,
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“the \mathbf{M}_i and \mathbf{v} are precise enough” \Rightarrow “the inclusion \subset is an equality”.

In particular, if $d = r$ then we can certify that the orbit is equal to \mathbb{C}^r .

Hybrid algorithm
for
factoring differential operators

Reconstructing a right-hand factor from a seed vector v

Proposition: $\mathcal{A}v \simeq \text{Sol}(P_f)$ where $P_f :=$ minimal annihilator of f

Hermite–Padé approximants

Given $f, f', \dots, f^{(r-1)} \in \overline{\mathbb{K}}[[x]]$, find $p_0, \dots, p_{r-1} \in \overline{\mathbb{K}}[x]$ of degree $\leq d$ such that $\sum_{i=0}^{r-1} p_i f^{(i)} = o(x^\sigma)$. ($\sigma < r(d+1) \Rightarrow$ nonzero solutions)

- ▶ if we find a candidate right-hand factor (using LLL algorithm to guess coefficients in $\overline{\mathbb{K}}$), we can check it by Euclidean division in $\overline{\mathbb{K}}(x)\langle\partial\rangle$.

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- ▶ if we find a candidate right-hand factor (using LLL algorithm to guess coefficients in $\overline{\mathbb{K}}$), we can check it by Euclidean division in $\overline{\mathbb{K}}(x)\langle\partial\rangle$.
- ▶ irreducible case? Two approaches:
 - **either** orbit computation to certify that $\mathcal{A}v = \mathbb{C}^{r \times 1}$
price: a complete set of generators of \mathcal{A} is *a priori* needed
 - **or** Hermite–Padé approximants to certify that $\text{order}(P_f) = r$
price: computations at a large order of truncation
($\sigma > rB$ where B is a degree bound for right-hand factors)
[Bostan, Rivoal, Salvy, 2019]

Input: $P \in \mathbb{K}(x)\langle \partial \rangle$ of order r

Output: ‘Irreducible’ or a nontrivial proper right-hand factor of P

1. Initialize the working precision p and the order of truncation σ
2. **While** a complete set of generators of \mathcal{A} has not been computed:
 - 2.a. Compute a new local monodromy matrix
 - 2.b. Choose randomly a combination M of the computed generators
 - 2.c. Try Norton’s criterion or another method depending on the spectrum of M
 - 2.d. If the previous step succeeds then return the result
3. Increase p and σ , and go back to line 2

Lemma [Eberly, 1991]

The set $\{M \in \mathcal{A} \text{ without simple eigenvalue}\}$ is an algebraic subset of \mathcal{A} .

Note: Local-to-global method \simeq 1st iteration of **While** loop

Experiments

operator	order, degree in x	classic (\mathbb{W})	new (\mathbb{E})	
rand (\mathbb{M})	4, 20	6.4s	9.6s	} local-to-global method applies
	6, 30	980s (!)	370s	
rand \times rand (\mathbb{M}) (different factors)	4, 20	11s	1.9s	
	6, 30	220s	22s	
rand (\mathbb{M})	4, 20	1400s	25s	} local-to-global method does not apply
	6, 30	2900s (!)	270s	
rand \times rand (\mathbb{M}) (different factors)	4, 20	1700s	8.4s	
	6, 30	14000s (!)(!!)	98s	
fcc5 (\mathbb{Y})	6, 17	62s	2.0s	} combinatorial examples
fcc6 (\mathbb{Y})	8, 43	>36000s	30s	

(\mathbb{W}) command `DFactor(_, 'one step')` of the Maple package `DEtools`

(\mathbb{E}) command `rfactor(_)` of my branch of `ore_algebra` SageMath package, at https://github.com/a-goyer/ore_algebra/tree/facto under the GNU GPL

(\mathbb{M}) random irreducible operators, created following [Ince, 1926]

(\mathbb{Y}) irreducible operators at <http://koutschan.de/data/fcc1/> (probabilistic walks)

(!) Warning message: "factorization of ... may be incomplete" (!!) Factorization is incomplete

Contributions

- ▶ Incremental hybrid algorithm + implementation in progress
- ▶ Link between local-to-global approach and Norton's criterion
- ▶ Package for symbolic-numeric factorization + validation

Remaining work

- ▶ Further timing comparisons between the different approaches
- ▶ Complexity analysis
- ▶ Extension to non-regular case
- ▶ Further possible applications?
 - Exponential/Liouvillian solutions
 - Decide whether there is a basis of algebraic solutions
 - The differential Galois group or its Lie algebra
 - Absolute factorization



Alin Bostan, Tanguy Rivoal, and Bruno Salvy.

Explicit degree bounds for right factors of linear differential operators.

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J. Della Dora and E. Tournier.

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Derek F. Holt and Sarah Rees.

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Journal of the Australian Mathematical Society, 57(1):1–16, 1994.



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Dover Publications, New York, 1926.



Claude Mitschi and David Sauzin.
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Journal of Symbolic Computation, pages 236–264, 2007.



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